

Exercise 1.41

Tyner

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A system with N degrees of freedom has coordinates $\{x_i\}$ and momenta $\{p_i\}$, $i = 1, \dots, N$. Consider that $\{x_i\}$ is written as a column vector \vec{x} . A transformation to new coordinates \vec{x}' is given by

$$\vec{x}' = \bar{M} \vec{x}$$

where the elements of the $N \times N$ matrix, \bar{M} , are constants.

a) If we write

$$\vec{p}' = \bar{Q} \vec{p}$$

what is the relation between \bar{Q} and \bar{M} that ensures that the transformation is canonical?

b) Under what conditions will the transformation be canonical if $\bar{Q} = \bar{M}$?

A transformation is canonical if

$$[q'_i, q'_j] = [p'_i, p'_j] = 0$$

$$[q'_i, p'_j] = \delta_{ij}$$

For a) we have

$$q'_i = \sum_{m=1}^N M_{im} q_m, \quad p'_i = \sum_{m=1}^N Q_{im} p_m$$

So, the conditions become

$$[q'_i, q'_j] = \sum_{k=1}^N \left(\frac{\partial q'_i}{\partial q_k} \frac{\partial q'_j}{\partial p_k} - \frac{\partial q'_j}{\partial q_k} \frac{\partial q'_i}{\partial p_k} \right) = 0$$

$$[p'_i, p'_j] = \sum_{k=1}^N \left(\frac{\partial p'_i}{\partial q_k} \frac{\partial p'_j}{\partial p_k} - \frac{\partial p'_j}{\partial q_k} \frac{\partial p'_i}{\partial p_k} \right) = 0$$

$$[q'_i, p'_j] = \sum_{k=1}^N \left(\frac{\partial q'_i}{\partial q_k} \frac{\partial p'_j}{\partial p_k} - \frac{\partial p'_j}{\partial q_k} \frac{\partial q'_i}{\partial p_k} \right) = \sum_{k=1}^N M_{ik} Q_{jk} = \delta_{ij}$$

In matrix notation we have

$$\bar{M} \bar{Q}^T = \bar{I} \quad \bar{M}^T \bar{Q} = \bar{I} \Rightarrow \bar{Q} = (\bar{M}^T)^{-1} = (\bar{M}^{-1})^T$$

So, for b) we would have $\bar{M}^T = \bar{M} = \bar{I} \Rightarrow \bar{M}^T = \bar{M}^{-1}$. That is, \bar{M} is an orthogonal matrix.